

# ROM Simulation with Exact Means, Covariances, and Multivariate Skewness

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# Motivation

- ▶ In many areas of finance (e.g., option pricing, risk management), numerical methods are required
- ▶ Example: simulation of (discrete) return distributions
- ▶ Generally desirable: “good fit” between simulated returns and some pre-specified distribution (e.g., Binomial model, number of time steps)

# Motivation

- ▶ One approach to achieve “good fit”: impose restrictions that ensure matching the first few moments of some pre-specified distribution
- ▶ For univariate distributions: easy. For multivariate distributions: Hoyland/Kaut/Wallace (2003), but confined to covariance matrix and higher marginal moments.
- ▶ What about higher moments beyond marginal moments? In particular, what about multivariate skewness?
- ▶ Downside risk. . . increased correlations in times of crises. . . many asset classes affected!

# Motivation

- ▶ Goal: generate discrete samples of multivariate distributions (risk factors, asset returns, ...)
- ▶ For  $n$  assets/risk factors with expected (excess) returns  $\mu_n$ , covariance matrix  $\mathbf{S}_n$ , and  $m$  different states of nature, find

$$\mathbf{X}_{mn} = \begin{bmatrix} X_{11} & X_{12} & \dots & X_{1n} \\ X_{21} & X_{22} & \dots & X_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ X_{m1} & X_{m2} & \dots & X_{mn} \end{bmatrix}$$

such that

$$m^{-1}(\mathbf{X}_{mn} - \mathbf{1}_m \mu_n')'(\mathbf{X}_{mn} - \mathbf{1}_m \mu_n') = \mathbf{S}_n.$$

Motivation

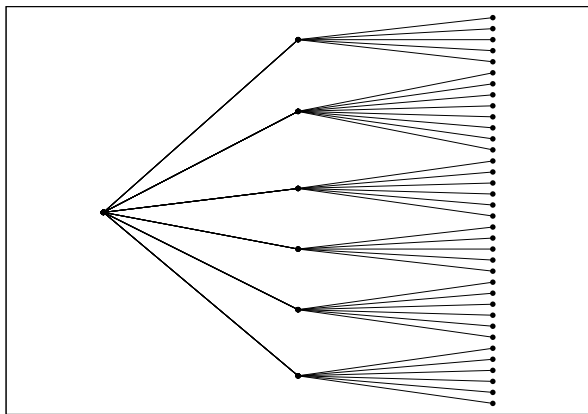
ROM simulation

Multivariate higher moments

ROM simulation matching also multivariate skewness

Conclusion

# Motivation



# Motivation

- ▶ Basis for our approach: Ledermann et al. (2011) (ROM simulation – multivariate samples matching pre-specified means and covariances)
- ▶ Additional requirements:
  - ▶ If  $\mathbf{X}_{mn}$  represents asset returns, make sure that they do not allow for arbitrage opportunities → “No-arbitrage ROM simulation”, Geyer/Hanke/Weissensteiner (JEDC, 2014)
  - ▶ If  $\mathbf{X}_{mn}$  should not only have pre-specified  $\mu_n$  and  $\mathbf{S}_n$ , but also “the correct skewness” → this paper. Correct skewness may be important for both (non-traded) risk factors and returns of (traded) assets

## ROM Simulation (Ledermann et al., 2011)

- ▶  $n$  assets with expected (excess) returns  $\boldsymbol{\mu}_n$  and covariance matrix  $\mathbf{S}_n$
- ▶ Goal: generate a sample  $\mathbf{X}_{mn}$  of  $m$  observations on the  $n$  random variables such that

$$m^{-1}(\mathbf{X}_{mn} - \mathbf{1}_m \boldsymbol{\mu}'_n)'(\mathbf{X}_{mn} - \mathbf{1}_m \boldsymbol{\mu}'_n) = \mathbf{S}_n. \quad (1)$$

- ▶  $\mathbf{S}_n$  can be decomposed (since pos. semi-def.) into  $\mathbf{S}_n = \mathbf{A}'_n \mathbf{A}_n$  (using, e.g., Cholesky decomposition)

# ROM Simulation

- ▶ Defining

$$\mathbf{L}_{mn} = m^{-1/2}(\mathbf{X}_{mn} - \mathbf{1}_m \boldsymbol{\mu}'_n) \mathbf{A}_n^{-1}, \quad (2)$$

solving (4) is equivalent to finding a matrix  $\mathbf{L}_{mn}$  satisfying

$$\mathbf{L}'_{mn} \mathbf{L}_{mn} = \mathbf{I}_n \quad \text{with} \quad \mathbf{1}'_m \mathbf{L}_{mn} = \mathbf{0}'. \quad (3)$$

- ▶ Ledermann (2011) call solutions to eq. (3) *L matrices*



# Mechanics of ROM simulation

- ▶ In general: pre-multiply an  $L$  matrix by a permutation matrix and post-multiply this product by any square orthogonal matrix  $\mathbf{R}_n$
- ▶ Pre-multiplication is primarily for controlling the time-ordering of random samples (not relevant here)
- ▶ The basis for Geyer et al. (2014) and for this paper is the following simplified version:

$$\mathbf{X}_{mn} = \mathbf{1}_m \mu'_n + \sqrt{m} \mathbf{L}_{mn} \mathbf{R}_n \mathbf{A}_n \quad (4)$$

# ROM simulation

- ▶ Since we will frequently need the scaled  $L$  matrix with column variance equal to 1, we define  $\mathbf{L} = \sqrt{m}\mathbf{L}_{mn}$
- ▶ Ledermann et al. (2011) suggest using matrices  $\mathbf{R}_n$  representing randomized rotation angles and directions
- ▶ Main insight of Geyer et al. (2014): “wise choice” of rotation directions combined with restricted intervals for random rotation angles ensures absence of arbitrage

# Multivariate higher moments

- ▶ So far, multivariate skewness and kurtosis measures are not very common in finance
- ▶ Recently, skewed multivariate distributions received increased attention in financial modeling
- ▶ Most frequently used in the literature: Mardia (1970) skewness and kurtosis measures
- ▶ Criticized by Kollo (2008) for being overly aggregated/simplistic
- ▶ Kollo (2008) develops informationally richer measures for multivariate skewness and kurtosis

## Co-skewness matrix

- Given  $n$  asset returns  $\mathbf{r} = (r_1, \dots, r_n)'$ , with means  $\bar{\mathbf{r}}$  and covariance matrix  $\Sigma$ , their  $(n \times n^2)$  co-skewness matrix  $\mathbf{M}_3$  can be defined as follows:

$$\mathbf{M}_3 = [\mathbf{D}_1 | \mathbf{D}_2 | \dots | \mathbf{D}_n], \quad (5)$$

where

$$\mathbf{D}_i = \begin{bmatrix} d_{i11} & d_{i12} & \dots & d_{i1n} \\ d_{i21} & d_{i22} & \dots & d_{i2n} \\ \vdots & & \ddots & \vdots \\ d_{in1} & d_{in2} & \dots & d_{inn} \end{bmatrix}, \quad (6)$$

$$d_{ijk} = \mathbb{E}[\mathbf{r}_i^* \mathbf{r}_j^* \mathbf{r}_k^*], \quad (7)$$

$$\mathbf{r}^* = \Sigma^{-1/2}(\mathbf{r} - \bar{\mathbf{r}}). \quad (8)$$

# Multivariate skewness measures

- ▶ Using the entire co-skewness matrix  $\mathbf{M}_3$  is impractical ( $n^3$  elements).
- ▶ Multivariate skewness measures aggregate the information contained in  $\mathbf{M}_3$ .
- ▶ In this aggregation, some information contained in  $\mathbf{M}_3$  gets lost.
- ▶ There is no universal best way to construct a multivariate skewness measure.
- ▶ In finance and financial risk management, retaining directional information is particularly desirable.

## Mardia's skewness measure

- ▶ In terms of the co-skewness matrix  $\mathbf{M}_3$ , Mardia's skewness measure is a scalar:

$$\tau_M(\mathbf{M}_3) = \sum_{ijk} d_{ijk}^2, \quad (9)$$

with  $d_{ijk}$  as defined in equation (7).

- ▶ The resulting skewness value is a scalar, which may be identical for distributions of very different shape.
- ▶ Mardia's skewness (and kurtosis) measures are criticized by Kollo (2008) based on an analysis of their shortcomings in Gutjahr (1999).
- ▶ Adding to this list, Mardia's skewness measure disregards the sign of co-skewness terms (!)

## Kollo's skewness measure

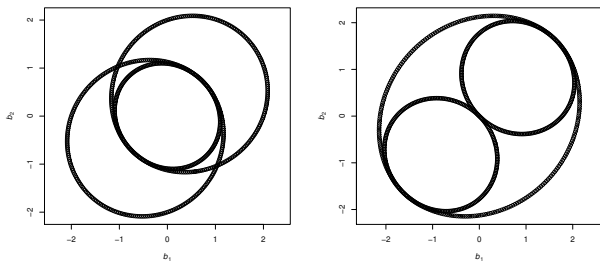
- ▶ Kollo (2008) defined an alternative, richer measure of skewness:

$$\mathbf{b}(\mathbf{M}_3) = \begin{pmatrix} \sum_{i1k} d_{i1k} \\ \sum_{i2k} d_{i2k} \\ \vdots \\ \sum_{ink} d_{ink} \end{pmatrix}, \quad (10)$$

with  $d_{ijk}$  as defined in equation (7).

- ▶ The resulting skewness value is a vector, not a scalar as in the case of Mardia's skewness.
- ▶ In most cases, Kollo's skewness measure retains more information compared to Mardia's skewness when aggregating co-skewness terms.

# Mardia and Kollo skewness of samples generated using ROM simulation



**Figure :** Examples of attainable Kollo skewness vectors  $\mathbf{b} = (b_1, b_2)'$  for  $m=4$  and  $n=2$  using two different  $L$  matrices. The Mardia skewness of the first matrix is  $2/3$ , and that of the second matrix is  $3$ .



## What values of Kollo skewness are attainable?

- ▶ The maximum norm of the Kollo skewness (when using the distance-of-one-vertex-maximizing simplex described in Geyer et al., 2014) is attained when each element of the skewness vector  $\mathbf{b}$  is given by

$$b^* = (m - 2)\sqrt{n/(m - 1)}, \quad (11)$$

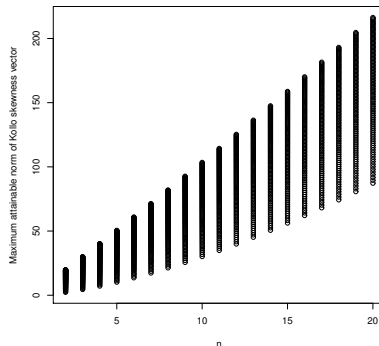
which results in a norm of

$$\|\mathbf{b}^*\| = \frac{n(m - 2)}{\sqrt{m - 1}}. \quad (12)$$

- ▶ This relation provides an additional lower bound for the number of states to be used for ROM simulation.

## What values of Kollo skewness are attainable?

- ▶ Fig. 2 shows max. attainable norms of Kollo skewness vectors for different dimensions  $(m, n)$ .  $m=n+2, \dots, n+100$ .



# ROM simulation matching also multivariate skewness

- ▶ Let us assume that a given skewness vector  $\mathbf{b} = (b_1, b_2, \dots, b_n)'$  is attainable
- ▶ Let  $\mathbf{L} = \sqrt{m}\mathbf{L}_{m,n}$  be a (scaled)  $L$  matrix with Kollo skewness  $\mathbf{b}$
- ▶ Use  $m \geq 4$  (and also  $m \geq n + 2$ ) as a minimal condition for the sample size
- ▶ Recall that

$$\mathbf{1}'_m \mathbf{L} = 0 \text{ and } \mathbf{L}'\mathbf{L} = m\mathbf{I}_n \quad (13)$$

# ROM simulation matching also multivariate skewness

- ▶ The problem of finding  $\mathbf{L}^*$  with a pre-specified Kollo skewness vector  $\mathbf{b}^*$  can be expressed as a system of linear, quadratic, and cubic equations
- ▶ This system can be simplified to finding the roots of one cubic equation, followed by solving a pair of linear and quadratic equations
- ▶ For details, see Section 4 of the paper

## Computation times

$m$	$n$			
	5	10	50	100
$n+2$	0.01 (0.00)	0.03 (0.01)	0.75 (0.03)	5.19 (0.21)
$2n$	0.01 (0.00)	0.05 (0.01)	2.54 (0.03)	17.91 (0.35)
$3n$	0.01 (0.00)	0.05 (0.01)	2.66 (0.09)	20.55 (0.84)
$4n$	0.01 (0.00)	0.05 (0.01)	2.89 (0.07)	20.61 (0.38)

**Table :** Average computation time in seconds (standard deviation in brackets) required to simulate  $m$  observations on  $n$  random variables with a random target Kollo skewness vector. Averages and standard deviations have been computed from 10 random vectors per problem size  $(m, n)$ .

## Conclusion

- ▶ Extension of original ROM simulation: Match also Kollo skewness in addition to means and covariances
- ▶ Potential applications: Large-scale risk management simulations (banks), other problems in finance
- ▶ No-arbitrage can be addressed by combining theoretical results on required sample size (Geyer et al., 2014) with “check – discard – resample”-loop
- ▶ Algorithm is very fast – for a given number of random variables (e.g., risk factors), computation time increases only slowly in the number of observations
- ▶ Further research: extension of the algorithm to match also Kollo kurtosis.

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## Publication details

Michael Hanke, Spiridon Penev, Wolfgang Schief, and Alex Weissensteiner: “Random Orthogonal Matrix Simulation with Exact Means, Covariances, and Multivariate Skewness”, *European Journal of Operational Research*, Vol. 263 (2), Dec. 2017, 510-523

# No-arbitrage ROM simulation

- ▶  $L$  matrices as defined before have zero mean
- ▶  $\mathbf{Y}_{mn} = \mathbf{X}_{mn} - \mathbf{1}_m \boldsymbol{\mu}'_n$  will be important, which can be computed from  $\mathbf{L}_{mn}$  using eq. (2):

$$\mathbf{Y}_{mn} = \sqrt{m} \mathbf{L}_{mn} \mathbf{A}_n \equiv \mathbf{L} \mathbf{A}_n \quad (14)$$

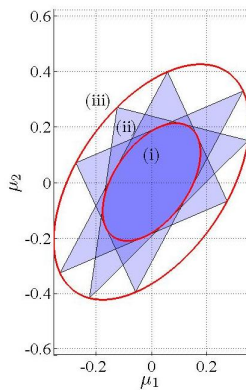
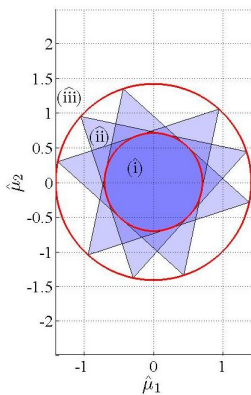
- ▶  $\mathbf{Y}_{mn}$  is linked to  $\mathbf{L}_{mn}$  by a particular affine transformation  $\mathcal{A}(\cdot)$ ,  $\mathbf{Y}_{mn} = \mathcal{A}(\mathbf{L}_{mn})$
- ▶  $\mathbf{Y}_{mn}$  can be interpreted as a sample of asset returns with the correct covariance structure  $\mathbf{S}_{mn}$  and means of  $\mathbf{0}_n$



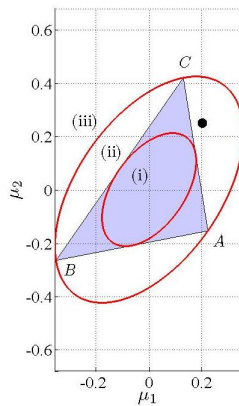
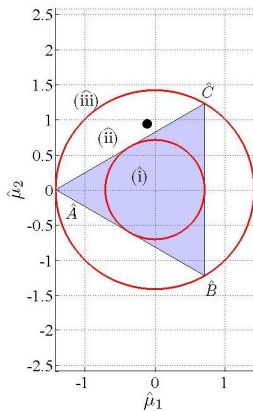
## No-Arbitrage ROM Simulation (Geyer et al., 2014)

- ▶ Geometric interpretation of  $L$  matrices: Rows of  $-\mathbf{L}_{mn}$  define a simplex (can be constructed deterministically)
- ▶ This simplex is regular if  $m=n+1$  (“complete market” with  $n$  risky assets and one risk-free asset), and irregular if  $m>n+1$  (“incomplete market”)
- ▶ Multiplying the simplex by  $\mathbf{R}_n$  rotates the simplex
- ▶ Absence of arbitrage means that expected excess returns  $\mu_n$  are inside the simplex
- ▶ Key insight:  $\mathbf{R}_n$  can be chosen judiciously to ensure that  $\mu_n$  is inside the simplex

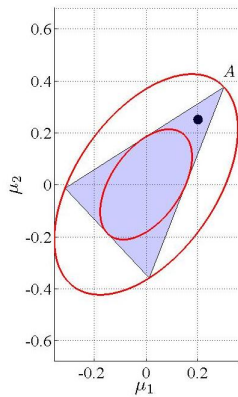
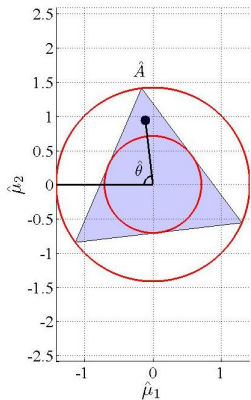
## Two-dimensional case



## Two-dimensional case



## Two-dimensional case



## Generalization to $n$ dimensions

- ▶ Equilateral triangle changes to a regular  $n$ -simplex
- ▶ In- and circumcircles of the triangle become hyperspheres, whose images are hyperellipsoids
- ▶ Deterministic construction of the simplex easily generalizes to  $n$  dimensions
- ▶ Rotation in  $n$  dimensions is a bit more tricky. . .